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# Dr. TAMER KHATTAB



# Presentation Title



# Bio data

CubeSat at Qatar University: Amateur Satellites as Educational and Capacity Building Platform

In this presentation, we will discuss standardized pico-satellites called CubeSat and their potential as capacity building and educational tools. The presentation will discuss the key features of CubeSat design and implementation. The presentation will also discuss the initiative of the CubeSat multidisciplinary project at Qatar University and its potential future progress.

Tamer Khattab received the B.Sc. and M.Sc. degrees in electronics and communications engineering from Cairo University, Giza, Egypt, in 1993 and 1999, respectively and the Ph.D. degree in electrical and computer engineering from The University of British Columbia (UBC), Vancouver, BC, Canada, in 2007. From 1994 to 1999, he was with IBM wtc, Giza, Egypt, as a development team lead. From 2000 to 2003, he was with Nokia (formerly Alcatel Canada Inc.), Burnaby, BC, Canada, as a senior member of the technical staff. He joined Qatar University (QU) in 2007, where he is currently a Professor of Electrical Engineering and the Director of the Center for Excellence in Teaching and Learning (CETL). He is also a senior member of the technical staff with Qatar Mobility Innovation Center (QMIC). His research interests cover satellite and aerial communications, information theory, and RF sensing techniques. He has recently started exploring the emerging area of quantum communications. He served as an editor for the IEEE Communication Letters, IEEE Transactions on Communications and IEEE Open Journal of the Communications Society. He is currently leading the Intelligent Information Processing Lab (IIPL) at Qatar University and the CubeSat project.





The CubeSat System Design



# QUBSat: Qatar University cuBeSat project A students' mega project

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# Outline



- Introduction
- Motivation and historical background
- A briefing on CubeSat
- 2 CubeSat System
  - The orbital deployer (P-POD)
  - The CubeSat standards
- The CubeSat System Design
  - Design
  - Subsystems Details





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Motivation

# Motivation and History of CubeSat

- Space technology is traditionally moving towards larger more complex and high cost systems
- Technology was only available to few large scale organizations that can afford the required resources
- In the last decade interest was in small scale low cost and complexity space systems with high power efficiency
- In 1999 CubeSat was originally conceived at Stanford University's Space Systems Development Laboratory joint with California Polytechnic State University (Cal Poly)
- The launching and standardization process is maintained and handled by Cal Poly



CubeSat System

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CubeSat System

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CubeSat

## What is CubeSat?

In a nutshell

#### CubeSat

A standardized, low cost, low complexity and very small satellite (called pico-satellite) that can be built using commercial off-the-shelf (COTS) components, can be adopted for different missions and allows for batch (multiple) low cost launching into orbit.







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CubeSat

### What is CubeSat? Properties

- Standardized in terms of its mechanical properties
- Low cost due to its standardization, mission choice and orbital choice
- Low complexity due to its orbital and mission choices
- Small size and low weight by design and standardization choice



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CubeSat

### What is CubeSat? Benefits

- Utilizes COTS because of its standardization and high interest
- Flexible mission by nature of satellite systems design and limited scope of standardization as well as availability of COTS
- Low cost launching due to availability of batch launching stemming from standardization and small size



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P-POD

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#### P-POD

### The poly-picosatellite orbital deployer (P-POD) Characteristics

- Standardized deployer maintained by Cal Poly
- Driven by the need for consistency in design and launching to enable batch launching







#### P-POD

### The poly-picosatellite orbital deployer (P-POD) Objectives

- Protect the primary payload
- Protect the launch vehicle
- Protect the CubeSats
- Safely group multiple CubeSats for launch
- Eject CubeSats for safe deployment
- Increase access to space for CubeSats
- Provide a standard interface to launch vehicles



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#### P-POD

### The poly-picosatellite orbital deployer (P-POD) Specifications

- Aluminum box of tubular design
- Has an ejection spring for non-explosive release.
- Can accommodate up to three 1U CubeSats.



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Standards

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Standards

### The CubeSat standards General specifications

- 10cm cube (called 1U)
- Can be 2U up to 12U maximum
- Maximum weight per 1U is 1.33kg





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Standards

### The CubeSat standards Categorizations

The requirements can be categorized into

- General
- Mechanical
- Electrical
- Operational





Standards

### The CubeSat standards The role of Cal Poly

Traditionally Cal Poly is the organization responsible for:

- Maintaining the CubeSat standards
- Developing, testing and flying the P-POD
- Coordinating CubeSat developers and launch providers.
- Coordinating launches for CubeSat





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### Requirements





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## **Environmental Constraints**

- Satellites flying in Low Earth Orbit (LEO) have the following environmental constraints:
- Operational temperature (-50°C to +150°C)
- Vacuum → outgassing and thermal dissipation
- Radiations → Single Event Latch-up (SEL)
- Radiations → Single Event Up-set (SEU)
- Distance (telecommunication)



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#### System Design

### The CubeSat Subsystems

### SPACECRAFT Structure: Launch interface, Materials, Launch Loads Power: Solar Panels, Batteries, Conditioning, Distribution Communication: Transmission, Reception, Conditioning & Routing of mission data. Command & Data Handling: Validation, Decoding & Distribution of commands. Attitude Determination & Control: Sensors, Actuators & Controlling Algorithms. Ground Station: Satellite Tracking, Satellite Communication, Data Processing, Storage Facility. Propulsion: Thrusters, Fuel, Tankage & Pipes Thermal Control: Insulation, Coatings, Louvers, Heaters



System Design

Orbit

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### Structure





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### Attitude Control - Passive





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### Attitude Control - Active

- Magnets control PICPOT attitude only about two axes
- To achieve three axes control, a reaction wheel is mounted on the x-axis
- · It is driven by a MAXON brushless motor
- Attitude control is not autonomous and requires ground intervention (autonomous control is not necessary to take pictures of Europe)
- The main interest lies in testing the reaction wheel itself

Maxon EC 32 flat motor data	Value	
Power rating [W]	6	
Nominal voltage [V]	9	
No load speed [rpm]	8600	
Stall torque [mNm]	20	
No load current [mA]	110	
Max. continuous current at 5000 rpm [A]	1.03	
Rotor inertia [g*cm²]	13.9	
Weight [g]	32	
Ambient temperature range [°C]	-40/+100	





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### Power System - Components



















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### Power System - Budgeting

Power sink	Duty cycle (%)	Power when active (mW)	Avg. power (mW)
Payload cameras: active only when triggering a photo; max 2s every orbit	0.03	1,200	3.6
Payload image compressor: active only after triggering a photo; max 30s every orbit, or 150s every 5 orbits	0.5	1,320	6.6
Payload communication to on-board data handling: active only while transmitting a photograph after triggering a photo; max 50s every orbit, or 250s every 5 orbits	0.8	1,320	10.5
Standard telemetry transmission, 435MHz: active max. 2s every minute	3.33	5,600	185
Extended telemetry and payload transmission, 435MHz; additional power when inside the ground station horizon: 53s each min when inside the horizon (avg 5 min every orbit; 5 orbits every twelve)	1.84	5,600	103
Standard telemetry transmission, 2.4GHz: active max. 2s every minute	3.33	3,000	100
Extended telemetry and payload transmission, 2.4GHz; additional power when inside the ground station horizon; 53s each min when inside the horizon (avg 5 min every orbit, 5 orbits every twelve)	1.84	3,000	55
TOTAL			495
Margins & derating (+50%)			247
TOTAL		1	742



System Design

### Power System - Sources ...

- > Five solar panels, which cover as many faces of the satellite.
- Each solar panel is about 4"x4", that is 100mm<sup>2</sup>.
- By taking into account that:
  - only one or at most two panels are exposed at a time at sunlight;
  - · when one panel, it is perpendicular to sunlight;
  - when two panels, they are 45° from sunlight to panel;
  - only one or two panels are exposed at Earth albedo (30% of sunlight)
- > Total equivalent panel surface is about 150mm<sup>2</sup>.
- Sun power density at LEO is about 1,200 W/m<sup>2</sup>
- Average persistence of satellite in the day is about 60%
- Total average power from sun is about 11.2W.
- Average efficiency of solar panels, over the expected temperature range (0÷60°C) is 23%, which we derate to 20%.
- Average electrical power from solar panels is 2.24W (averaged over a number of orbits; worst case for temperature and derating)



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System Design

### Power System - Sources

- > Energy is stored on a collection of six packs of rechargeable batteries
- Two groups of three packs (each pack supplies half satellite, for redundancy)
- Each pack contains either two Li-P element or six NiCd element
- 7.2V typical for each pack. Capacity is 1.5 Ah (10.8Wh) for Li-P and 0.9Ah (6.5Wh) for NiCd. Max. available energy is then 56.2Wh.
- Each pack in turn is charged from the five solar panels via an hysterethic switching supply.
- Worst case efficiency of charger is 70% = 1.56W to recharge batteries.
- Worst case efficiency of battery is 75% (over temperature, after 60 cycles = three months of expected and properly derated for radiation)
- Expected recharge time is 12.2h (Li-P) and 7.3h (NiCd).
- > Total recharge time for the whole satellite is therefore **63.4h**.
- It results an average power available for all electronic systems of 1.17W
- Total storage time of about 2.5 days (all batteries fully charged; avg. power consumption of 820mW).



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### **Onboard Computer - Requirements**

On-board data handling processors are required to:

- Communicate with ground station (via RF channel)
- Acquire telemetry data every minute (50 sensors)
- Store telemetry statistics for one orbit (100 min)
- Control battery charging strategy



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# **Onboard Computer - Example**

Five processors on board:

- 1. Housekeeping A: Chipconn 1010
  - > 437.478 MHz commun. channel
- 2. Housekeeping B: Texas Instrument MSP430
  - > 2.440 GHz commun. channel
- 3. Payload: Analog Devices BlackFINN
  - image compression & storage
- 4. Timing generators: PIC16F706 + MSP430, replicating functions
- Processor A and B replicate the main housekeeping satellite functions.



The CubeSat System Design

#### System Design

### Communications Systems - Link Budgeting Downlink

Downlink		_					
	-						
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The CubeSat System Design

#### System Design

### Communications Systems - Link Budgeting Upnlink

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Summary 0000

System Design

### Communications Systems - Antenna





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### Communications Systems - Transceiver





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### **Communications Systems - Frequencies**

	Option 1	Option 2	Option 3	Option 4
Frequency Band (MHz)	144 <b>-</b> 146	420- 450	1260- 1270	2400- 2450



CubeSat System

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Summary

System Design

## Wiring and Shielding







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CubeSat System

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### Let's hope we reach there





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### Some QU folks are working on it





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### QU CubeSat ground station





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### QU CubeSat clean room







# Summary

- Affordable for universities.
- Multidisciplinary.
- Teamwork, system design and project planning.
- Started as student project and now has research funding.

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